

Robotics Subsidized R&D Programs

March 2013 (G.P. Gerio)



ECHORD FP7 Eu project

II call experiments









COMAU Open platform





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Il call experiments (Comau direct present in the consortium)



Proposal full title: Accurate Manual Guided robot programming

Proposal Acronym: EASYPRO

Name of the Coordinating Person: Alberto Tellaeche

Institution of the Coordinating Person: Fundación TEKNIKER

Proposal full title: Flxtureless DEburring of wheeLs by human demonstratIOn

Proposal Acronym: FIDELIO

Name of the Coordinating Person: Luca Bascetta

Institution of the Coordinating Person: Politecnico di Milano (Italy)

III call experiments (COMAU no direct presence in the consortium)



Proposal full title: **Ro**bust Control of Human-Robot-Environment **D**ynamic Interaction for **N**atural Stone Carving

Proposal Acronym: RODIN

Name of the Coordinating Person: Prof. Dr. Jörg Krüger

Institution of the Coordinating Person: Technische Universität Berlin, Institut für

Werkzeugmaschine und Fabrikbetrieb,

Fachgebiet Industrielle

Automatisierungstechnik, TUB-IAT



III call experiments (COMAU no direct presence in the consortium)



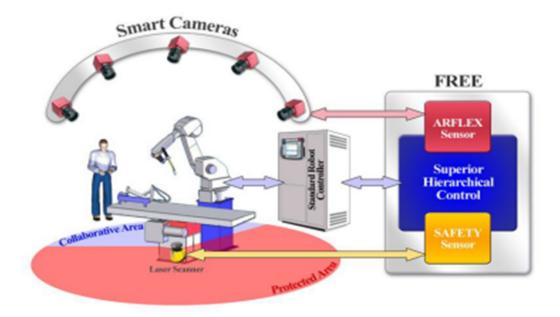
Proposal full title: Flexible and safe interactive human-Robot Environment

for small batch Exacting applications

Proposal Acronym: FREE

Name of the Coordinating Person: Gabriella Caporaletti

Institution of the Coordinating Person: EICAS Automazione S.p.A



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Final achieved global results:

For Comau Echord represents a good way to interacts with University, main achieved targets can be summarized in:

- Establishing new relationship during the 'experiments'
- Giving the opportunity to apply research to real Sme problems
- Less reporting activity, more concentrate in the Laboratory
- Improving University laboratory (use of equipment for future research and standard University activities for students)
- Create and improve the network of laboratory research